Mining query logs with topic models

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Objectives

- Modelling user interaction (relevance feedback)
- Improve image retrieval through indexing
- Incremental image annotation



Nature of the data (relevance feedback)

- Query-by-example paradigm
- User refines query by marking positive (+1) and negative (-1) examples from results
- Query is refined until the search terminates (successfully or not)

At any time, we have a collection of M images and N queries. The collection of relevance judgements can be represented as a matrix \mathcal{R} of co-occurrences:

Sessions



Topic modelling

- Goal: explain observed co-occurrences by estimating linear combinations of hidden factors
- Text modelling: Underlying topics are said to generate word observations in text documents
- In our case, the hidden factors are the users' intent during search as well as concepts or objects expressed in the images of the collection

Non-negative matrix factorisation (NMF)

Seek an approximation $\mathcal{R} \approx WH$ such that the Frobenius norm $||\mathcal{R} - WH||_F$ is minimised. We iterate update steps:

$$H_{cj} \leftarrow H_{cj} \frac{\sum_{i} \frac{W_{ic} \mathcal{R}_{ij}}{(WH)_{ij}}}{\sum_{i} W_{ic}}$$
(1)
$$W_{ic} \leftarrow W_{ic} \frac{\sum_{j} \frac{H_{cj} \mathcal{R}_{ij}}{(WH)_{ij}}}{\sum_{j} H_{cj}}$$
(2)

where W is the image-topic matrix and H is the topic-query matrix (Lee and Seung, 1999).

NMF constrains values in the co-occurrence matrix to be $\geq = 0$, so we scale our RF data (\mathcal{R}_{ii}) into this range:

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ightarrow 0 \ 0
ightarrow 0.5 \ 1
ightarrow 1 \end{array}$$

which can be loosely interpreted as the probability of an image d_i being relevant to a query q_j .

Singular value decomposition (SVD)

Any matrix \mathcal{R} can be rewritten in the form:

$$\mathcal{R} = U\Sigma V^T \tag{3}$$

where U are the left singular vectors, Σ are the singular values (square roots of the eigenvalues), and V^T are the right singular vectors.

A rank-k approximation to \mathcal{R} can be achieved by retaining the k largest singular values in Σ :

$$\mathcal{R}_k = U_k \Sigma_k V_k^{\mathsf{T}} \tag{4}$$

Orthonormality constraint:

$$U^{T}U = V^{T}V = I$$

||U|| = ||V|| = 1 (5)

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User Relevance Model (URM)

Extension of probabilistic latent semantic analysis (PLSA) (Hofmann, 1999)

- Generative, probabilistic model
- Documents and queries assumed to be generated from the same concept-space

Relevance judgement generation:

- generate a query with probability P(q)
- select latent concept with probability P(c|q)
- select a document with probability P(d)
- generate a relevance judgement P(r|d, c)

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User Relevance Model (URM)

Joint probability (co-occurrence observations) P(r, d, q) is defined as:

$$\mathcal{R} = P(r, d, q) = P(q)P(d)P(r|d, q), \tag{6}$$

where

$$P(r|d,q) = \sum_{c \in \mathcal{C}} P(r|d,c) P(c|q).$$
(7)

Following Bayes rule, we can rewrite the joint probability as:

$$P(r,d,q) = \sum_{c \in \mathcal{C}} P(c)P(q|c)P(d)P(r|d,c).$$
(8)

"Fit" of latent variables to observed data measured using log-likelihood:

$$\mathcal{L} = \sum_{d \in \mathcal{D}} \sum_{q \in \mathcal{Q}} \sum_{r} n(r, d, q) \log P(r, d, q).$$
(9)

Expectation-maximisation used to converge on a maximum \mathcal{L} .

Document similarity with topic models

- Models lend themselves to item/attribute similarity
- We can use these similarity graphs to propagate meta-data and index images

Image similarity using dot product:

- ► NMF: WW^T
- ► SVD: UU^T
- URM: $P(r|d, c)P(r|d, c)^T$



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Experiments

Corel image collection, 1000 images, 10 categories, 100 images per category, 3-5 annotations per image.

- Sparsity 95%
- ► Noise 10%
- 3000 artificial query sessions
- 10 latent variables

Image similarity experiments

Accuracy measured using *mean average precision*: each image used as a query; ranked list of most similar images yields a score closer to 1 the more the relevant images are ranked first (an indication of images clustered over latent topics)



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Image annotation experiments

For each unannotated image, rank top-I similar images and select w tags from the pool of W total tags.

Formally:

We repeat a draw $t_{1..w} \sim \mathcal{U}[1, W]$ (without replacement) for each unannotated image where w equals the desired number of annotations (w = 4).



Image annotation experiments



Original vocab size: 253; depleted vocab size: 153; unannotated images: 2

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Image annotation experiments

Accuracy measure: Euclidean distance between term-document matrices



Example annotations



(deer, grass, water, white-tailed)



bear,river,snow (bear,grizzly,stream,water)



dust, elephant, sky, water (bull, elephant, sky, water)



forest, snow, trees, wolf (grass, shade, trees, wolf)



head,lion,mane,rocks (cats,field,grass,lions)



grass, hippo, pair, river (grass, hippos, wallow, water)

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Conclusions

Conclusions

- Introduced a probabilistic User Relevance Model
- Recovery of underlying concepts from documents possible under sparse conditions
- Application to retrieval and image annotation

Future work

- Images with no tags can be brought to the attention of the user in order to ellicit interaction
- Tag quality could be improved by supplementing the RF judgements with low-level feature information (pseudo-relevance feedback)

Thank you

Questions



Thomas Hofmann. Probabilistic latent semantic analysis. In Proc. of Uncertainty in Artificial Intelligence, UAI'99, Stockholm, 1999. URL citeseer.ist.psu.edu/hofmann99probabilistic.html.

D. D. Lee and H. S. Seung. Learning the parts of objects by non-negative matrix factorization. Nature, 401(6755): 788-791, October 1999. ISSN 0028-0836. doi: http://dx.doi.org/10.1038/44565. URL http://dx.doi.org/10.1038/44565. Expectation-maximisation for URM

$$\mathcal{L} = \sum_{d \in \mathcal{D}} \sum_{q \in \mathcal{Q}} \sum_{r} n(r, d, q) \log P(r, d, q), \quad n(r, d, q) \in \{0, 1\}$$
(10)

E-step:

$$P(c|r,d,q) = \frac{P(c)P(q|c)P(r|d,c)}{\sum_{c \in \mathcal{C}} P(c)P(q|c)P(r|d,c)},$$
(11)

M-step:

$$P(q|c) \propto \sum_{d \in \mathcal{D}} \sum_{r} n(r, d, q) P(c|r, d, q), \qquad (12)$$

$$P(r|d,c) \propto \sum_{q \in \mathcal{Q}} n(r,d,q) P(c|r,d,q),$$
(13)

 and

$$P(c) = \frac{\sum_{d \in \mathcal{D}, q \in \mathcal{Q}, r} n(r, d, q) P(c|r, d, q)}{\sum_{d \in \mathcal{D}, q \in \mathcal{Q}, r} n(r, d, q)}.$$
 (14)